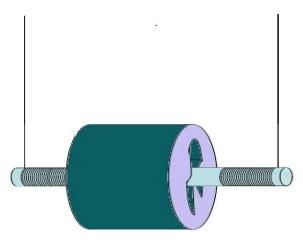
La roue de maxwell



Présenté par les étudiants :

Ould cherchali hocine

> Matériels :

- Base de support.
- Tige du support.
- Bloc ou vis de fixation.
- Règle métrique.
- Une paire d'indicateur.
- La roue de maxwell.
- Dispositif de support avec câble de déclanchement.
- Deux fils de connections.

Partie théorie :

On a la relation:

$$E_T = E_{potentielle} + E_{translation} + E_{rotation}$$

$$E_T=m.\,\vec{g}.\vec{s}+\frac{1}{2}m\vec{v}^2+\frac{1}{2}I_z\vec{\omega}^2$$

m: la masse de disque

g: accélération de gravitation

s : hauteur

v : vitesse de translation

I: moment d'inertie

ω: vitesse angulaire

D'après l'energie total est constante (conservation), alors

$$\frac{dE}{dt} = -m.g.v(t) + \left(m + \frac{I}{r^2}\right).v(t).\frac{dv}{dt} = 0$$

Manipulation

ullet En calcule t_{moy} et s_{moy} tel que

$$t_{moy} = \frac{t_1 + t_2 + t_3}{3}$$
 et $s_{moy} = \frac{s_1 + s_2 + s_3}{3}$

❖ En calcule les incertitudes

Pour la distance <u>"Δh"</u> on a :

$$\Delta s = \Delta s_{inst} + \Delta s_{lecture} + \Delta s_{mesure}$$

$$\Delta s_{inst} = 0.5mm \text{ , } \Delta s_{lecture} = 0.5mm \text{ , } \Delta s_{mesure} = max | s_i - s_{moy} |$$
 Pour le temps " δt ":

$$\delta t = \delta t_{inst} + \delta t_{lecture} + \delta t_{mesure}$$

$$\delta t_{inst} = 0.01s$$
 , $\delta t_{lecture} = 0 s$, $\delta t_{mesure} = max |t_i - t_{moy}|$

Pour le temps "\Dt":

$$\Delta t = \Delta t_{inst} + \Delta t_{lecture} + \Delta t_{mesure}$$

$$\Delta t_{inst} = 0.001s$$
 , $\Delta t_{lecture} = 0 s$, $\Delta t_{mesure} = max |t_i - t_{mov}|$

Application numérique :

$$\Delta s_1 = 0.2 \times 10^{-2} m$$

$$\Delta s_{inst} = 0.5mm , \Delta s_{lecture} = 0.5mm ,$$

$$\Delta s_{mesure} = max \left| s_i - s_{moy} \right| = 0.1 \times 10^{-2} m$$

$$\delta t_1 = 0.25s$$

$$\delta t_{inst} = 0.01s$$
 , $\delta t_{lecture} = 0 \ s$,

$$\delta t_{mesure} = max \left| t_i - t_{moy} \right| = 0.24s$$

$$\delta \Delta t_1 = 0.005 s$$

$$\delta \Delta t_{inst} = 0.001 s$$
 , $\delta \Delta t_{lecture} = 0 s$,

$$\delta \Delta t_{mesure} = max |t_i - t_{moy}| = 0.004s$$

$$\Delta s_2 = 0.3 \times 10^{-2} m$$

$$\Delta s_{inst} = 0.5mm$$
 , $\Delta s_{lecture} = 0.5mm$,
$$\Delta s_{mesure} = max \left| s_t - s_{mov} \right| = 0.2 \times 10^{-2} m$$

$$\delta t_2 = 0.03s$$

$$\delta t_{inst} = 0.01s$$
 , $\delta t_{lecture} = 0 s$,

$$\delta t_{mesure} = max \left| t_i - t_{moy} \right| = 0.02s$$

$\delta \Delta t_2 = 0.002 \, s$

$$\delta \Delta t_{inst} = 0.001 s$$
 , $\delta \Delta t_{lecture} = 0 s$,

$$\delta \Delta t_{mesure} = max \big| t_i - t_{moy} \big| = 0.001s$$

$\Delta s_3 = 0.3 \times 10^{-2} m$

$$\begin{split} \Delta s_{inst} &= 0.5mm \text{ ,} \Delta s_{lecture} = 0.5mm \text{ ,} \\ \Delta s_{mesure} &= max \left| s_i - s_{moy} \right| = 0.2 \times 10^{-2}m \end{split}$$

$$\delta t_3 = 0.14s$$

$$\delta t_{inst} = 0.01s$$
 , $\delta t_{lecture} = 0 s$,

$$\delta t_{mesure} = max |t_i - t_{moy}| = 0.13s$$

$\delta \Delta t_3 = 0.001 s$

$$\delta \Delta t_{inst} = 0.001s$$
 , $\delta \Delta t_{lecture} = 0 s$,

$$\delta \Delta t_{mesure} = max \left| t_i - t_{moy} \right| = 0.000 s$$

$\Delta s_4 = 0.2 \times 10^{-2} m$

$$\Delta s_{inst} = \mathbf{0.5}mm$$
 , $\Delta s_{lecture} = \mathbf{0.5}mm$,

$$\Delta s_{mesure} = max \left| s_i - s_{moy} \right| = 0.1 \times 10^{-2} m$$

$\delta t_4 = 0.05s$

$$\delta t_{inst} = 0.01s$$
 , $\delta t_{lecture} = 0 s$,

$$\delta t_{mesure} = max \left| t_i - t_{moy} \right| = 0.04s$$

$\delta \Delta t_4 = 0.001 s$

$$\delta \Delta t_{inst} = 0.001s$$
 , $\delta \Delta t_{lecture} = 0 s$,

$$\delta \Delta t_{mesure} = max \left| t_{\bar{t}} - t_{moy} \right| = 0.000 s$$

$\Delta s_5 = 0.3 \times 10^{-2} m$

$$\Delta s_{inst} = 0.5mm$$
 , $\Delta s_{lecture} = 0.5mm$,

$$\Delta s_{mesure} = max \left| s_i - s_{moy} \right| = 0.2 \times 10^{-2} m$$

$\delta t_5 = 0.16s$

$$\delta t_{inst} = 0.01s$$
 , $\delta t_{lecture} = 0 s$,

$$\delta t_{mesure} = max \left| t_i - t_{moy} \right| = 0.15 s$$

$\delta \Delta t_5 = 0.002 s$

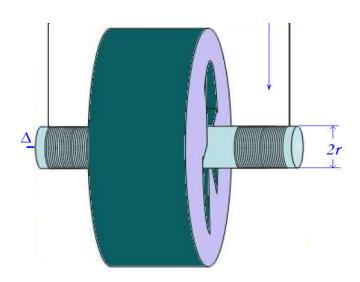
$$\delta \Delta t_{inst} = 0.001s$$
 , $\delta \Delta t_{lecture} = 0 s$,

$$\delta \Delta t_{mesure} = max |t_t - t_{moy}| = 0.001s$$

 \bullet En calcule les vitesses moyennes et l'incertitude ΔV :

$$V_{moy} = \frac{s_{moy}}{t_{moy}}$$

$$r = 2.5mm$$



$$\begin{split} V_{1\;moy} &= \frac{s_{1\;moy}}{t_{1\;moy}} = \frac{27.3 \times 10^{-2}}{4.54} = 6.01 \times 10^{-2} \, m/s \\ V_{2\;moy} &= \frac{s_{2\;moy}}{t_{2\;moy}} = \frac{41.1 \times 10^{-2}}{5.54} = 7.41 \times 10^{-2} \, m/s \\ V_{3\;moy} &= \frac{s_{3\;moy}}{t_{3\;moy}} = \frac{48.0 \times 10^{-2}}{6.26} = 7.66 \times 10^{-2} \, m/s \\ V_{4\;moy} &= \frac{s_{4\;moy}}{t_{4\;moy}} = \frac{37.9 \times 10^{-2}}{5.29} = 7.16 \times 10^{-2} \, m/s \\ V_{5\;moy} &= \frac{s_{5\;moy}}{t_{5\;moy}} = \frac{16.7 \times 10^{-2}}{3.38} = 4.94 \times 10^{-2} \, m/s \end{split}$$

$$\begin{split} V_{moy} &= \frac{s_{moy}}{t_{moy}} \quad \Rightarrow \frac{\Delta V}{V} = \frac{\Delta s}{s} + \frac{\delta t}{t} \quad \text{Donc:} \\ \Delta V &= V_{moy} \left(\frac{\Delta S}{s} + \frac{\delta t}{t} \right) \\ \Delta V_1 &= V_1 \,_{moy} \left(\frac{\Delta S_1}{s_1} + \frac{\delta t_1}{t_1} \right) = 6.01 \times 10^{-2} \left(\frac{0.2 \times 10^{-2}}{27.3 \times 10^{-2}} + \frac{0.25}{4.54} \right) = 0.0037 \, m/s \\ \Delta V_2 &= V_2 \,_{moy} \left(\frac{\Delta S_2}{s_2} + \frac{\delta t_2}{t_2} \right) = 7.41 \times 10^{-2} \left(\frac{0.3 \times 10^{-2}}{41.1 \times 10^{-2}} + \frac{0.03}{5.54} \right) = 0.0009 \, m/s \\ \Delta V_3 &= V_3 \,_{moy} \left(\frac{\Delta S_3}{s_3} + \frac{\delta t_3}{t_3} \right) = 7.66 \times 10^{-2} \left(\frac{0.3 \times 10^{-2}}{48.0 \times 10^{-2}} + \frac{0.14}{6.26} \right) = 0.0021 \, m/s \\ \Delta V_4 &= V_4 \,_{moy} \left(\frac{\Delta S_4}{s_4} + \frac{\delta t_4}{t_4} \right) = 7.16 \times 10^{-2} \left(\frac{0.2 \times 10^{-2}}{37.9 \times 10^{-2}} + \frac{0.05}{5.29} \right) = 0.0010 \, m/s \\ \Delta V_5 &= V_5 \,_{moy} \left(\frac{\Delta S_5}{s_5} + \frac{\delta t_5}{t_5} \right) = 4.94 \times 10^{-2} \left(\frac{0.3 \times 10^{-2}}{16.7 \times 10^{-2}} + \frac{0.16}{3.38} \right) = 0.0032 \, m/s \end{split}$$

❖ En calcule "t":

$$\dot{t} = t_{moy} + \frac{\Delta t_{moy}}{2}$$

$$\dot{t}_1 = t_{1 moy} + \frac{\Delta t_{1 moy}}{2} = 4.54 + \frac{0.055}{2} = 4.577s$$

$$\dot{t}_2 = t_{2 moy} + \frac{\Delta t_{2 moy}}{2} = 5.54 + \frac{0.039}{2} = 5.559s$$

$$\dot{t}_3 = t_{3 moy} + \frac{\Delta t_{3 moy}}{2} = 6.26 + \frac{0.035}{2} = 6.277s$$

$$\dot{t}_4 = t_{4 moy} + \frac{\Delta t_{4 moy}}{2} = 5.29 + \frac{0.040}{2} = 5.310s$$

$$\dot{t}_5 = t_{5 moy} + \frac{\Delta t_{5 moy}}{2} = 3.38 + \frac{0.070}{2} = 3.415s$$

 \bullet En calcule " Δt ":

$$\begin{split} \Delta \hat{t}_1 &= \delta t_1 + \delta \Delta t_1 = 0.250 + 0.005 = 0.255s \\ \Delta \hat{t}_2 &= \delta t_2 + \delta \Delta t_2 = 0.030 + 0.002 = 0.032s \\ \Delta \hat{t}_3 &= \delta t_3 + \delta \Delta t_3 = 0.140 + 0.001 = 0.141s \\ \Delta \hat{t}_4 &= \delta t_4 + \delta \Delta t_4 = 0.050 + 0.001 = 0.051s \\ \Delta \hat{t}_5 &= \delta t_5 + \delta \Delta t_5 = 0.160 + 0.002 = 0.162s \end{split}$$

* En calcule les vitesses instantanées.

$$V_{moy} = V_{inst} \left(t + \frac{\Delta t}{2} \right)$$

$$\begin{split} V_{inst} &= \frac{V_{moy}}{\left(t + \frac{\Delta t}{2}\right)} \\ V_{1 \ inst} &= \frac{6.01 \times 10^{-2}}{(4.577)} = 0.0131 \ m/s \\ V_{2 \ inst} &= \frac{7.41 \times 10^{-2}}{(5.559)} = 0.0133 \ m/s \\ V_{3 \ inst} &= \frac{7.66 \times 10^{-2}}{(6.277)} = 0.0122 \ m/s \\ V_{4 \ inst} &= \frac{7.16 \times 10^{-2}}{(5.310)} = 0.0134 \ m/s \\ V_{5 \ inst} &= \frac{4.94 \times 10^{-2}}{(3.415)} = 0.0144 \ m/s \end{split}$$

 \Leftrightarrow En trace le graphe V = f(t).

On a dans le graphe V=A. \dot{t}

Et théoriquement
$$V=rac{m.g}{m+rac{l}{r^2}}$$
 , t

Donc
$$A = \frac{m_n \mathbf{g}}{m + \frac{I}{n^2}}$$

Calculer $A_{min}et A_{max}$:

$$A_{min} = \tan 41.80 = 0.89$$

$$A_{max} = \tan 53.04 = 1.32$$

Calculer I_{min} et I_{max} :

$$A_{max} = \frac{m \cdot g}{m + \frac{I_{min}}{r^2}} \quad \Rightarrow I_{min} = r^2 m \left(\frac{g - A_{max}}{A_{max}} \right)$$

$$A_{min} = \frac{m.\,g}{m + \frac{I_{max}}{r^2}} \quad \Rightarrow I_{max} = r^2 m \left(\frac{g - A_{min}}{A_{min}}\right)$$

$$I_{min} = (0.25)^2 (0.4365) \left(\frac{9.81 - 1.32}{1.32} \right) = 0.175 \ kg/cm^2$$

$$I_{max} = (0.25)^2 (0.4365) \left(\frac{9.81 - 0.89}{0.89} \right) = 0.273 \ kg/cm^2$$

$$I_z = \frac{I_{max} + I_{min}}{2} = \frac{0.175 + 0.273}{2} = 0.224 \, kg/cm^2 = 2240 \, kg/m^2$$

$$\Delta I_z = \frac{I_{max} - I_{min}}{2} = \frac{0.273 - 0.175}{2} = 0.049 \, kg/cm^2 = 490 \, kg/m^2$$

Déterminer les différentes énergies :

On a la relation suivante

$$E_T = E_{potentialle} + E_{translation} + E_{rotation}$$

$$E_T = m.\,\vec{g}.\vec{s} + \frac{1}{2}m\vec{v}^2 + \frac{1}{2}I_z\vec{\omega}^2$$

✓ En calcule l'énergie potentielle

$$E_{P\ 1} = -m.g.s_{1\ moy} = -0.4365 \times 9.81 \times 27.3 \times 10^{-2} = -1.169 \ J$$

$$E_{P\ 2} = -m.g.s_{2\ moy} = -0.4365 \times 9.81 \times 41.1 \times 10^{-2} = -1.759 \ J$$

$$E_{P\ 3} = -m.g.s_{3\ moy} = -0.4365 \times 9.81 \times 48.0 \times 10^{-2} = -2.050 \ J$$

$$E_{P\ 4} = -m.g.s_{4\ moy} = -0.4365 \times 9.81 \times 37.9 \times 10^{-2} = -1.622 \ J$$

$$E_{P\ 5} = -m.g.s_{5\ moy} = -0.4365 \times 9.81 \times 16.7 \times 10^{-2} = -0.715 \ J$$

✓ En calcule l'énergie de translation

$$E_{t 1} = \frac{1}{2} m v_{1 moy}^2 = \frac{1}{2} (0.4365) (6.01 \times 10^{-2}) = 0.0131 J$$

$$E_{t 2} = \frac{1}{2} m v_{2 moy}^2 = \frac{1}{2} (0.4365) (7.41 \times 10^{-2}) = 0.0161 J$$

$$E_{t 3} = \frac{1}{2} m v_{3 moy}^2 = \frac{1}{2} (0.4365) (7.66 \times 10^{-2}) = 0.0167 J$$

$$E_{t 4} = \frac{1}{2} m v_{4 moy}^2 = \frac{1}{2} (0.4365) (7.16 \times 10^{-2}) = 0.0156 J$$

$$E_{t 5} = \frac{1}{2} m v_{5 moy}^2 = \frac{1}{2} (0.4365) (4.94 \times 10^{-2}) = 0.0107 J$$

✓ En calcule l'énergie de rotation

$$E_{R 1} = \frac{1}{2} I_{Z} \frac{V_{1}^{2}}{r^{2}} = \frac{1}{2} (0.224) \frac{(6.01 \times 10^{-2})}{(0.25)^{2}} = 0.107 J$$

$$E_{R 2} = \frac{1}{2} I_{Z} \frac{V_{2}^{2}}{r^{2}} = \frac{1}{2} (0.224) \frac{(7.41 \times 10^{-2})}{(0.25)^{2}} = 0.132 J$$

$$E_{R 3} = \frac{1}{2} I_{Z} \frac{V_{2}^{2}}{r^{2}} = \frac{1}{2} (0.224) \frac{(7.66 \times 10^{-2})}{(0.25)^{2}} = 0.137 J$$

$$E_{R 4} = \frac{1}{2} I_{Z} \frac{V_{4}^{2}}{r^{2}} = \frac{1}{2} (0.224) \frac{(7.16 \times 10^{-2})}{(0.25)^{2}} = 0.128 J$$

mécanique de l'énergie

$$E_{R.5} = \frac{1}{2}I_z \frac{V_5^2}{r^2} = \frac{1}{2}(0.224) \frac{(4.94 \times 10^{-2})}{(0.25)^2} = 0.088 J$$

Conclusion

Après les étapes qu'on a suivi on conclue qu'on peut calculer avec la roue de maxwell plusieurs paramètres : moment d'inertie, énergie potentielle, énergie de translation et l'énergie de rotation, et en plus en vérifie la loi de conservation

N°	S (m)	t (s)	∆ t (s)	$s_{moy}(m)$	$\Delta s\left(m ight)$	t _{moy} (s)	δt (s)	$\Delta t_{moy}(s)$	$\delta \Delta t (s)$
1	27.2 X 10⁻²	4.78	0.055	27.3X 10 ⁻²	0.2×10^{-2}	4.54	0.25	0.055	0.005
	27.4× 10 ⁻²	4.35	0.053						
	27.3× 10 ⁻²	4.47	0.059						
2	41.0× 10 ⁻²	5.53	0.039	41.1X 10 ⁻²	0.3×10^{-2}	5.54	0.03	0.039	0.002
	41.2× 10 ⁻²	5.54	0.040						
	41.3 X 10 ⁻²	5.56	0.039						
3	48.2× 10 ⁻²	6.32	0.035	48.0× 10 ⁻²	0.3×10^{-2}	6.26	0.14	0.035	0.001
	47.9× 10 ⁻²	6.35	0.035						
	48.0 × 10 ⁻²	6.13	0.035						
4	37.9× 10 ⁻²	5.33	0.040	37.9× 10 ⁻²	0.2×10^{-2}	5.29	0.05	0.040	0.001
	38.0× 10 ⁻²	5.30	0.040						
	38.0× 10 ⁻²	5.26	0.040						
5	16.9× 10 ⁻²	3.53	0.071	16.7× 10 ⁻²	0.3×10^{-2}	3.38	0.16	0.070	0.002
	16.7 X 10 ⁻²	3.25	0.070						
	16.5× 10 ⁻²	3.37	0.070						

